

NOTICE

All instructions, warranties and other collateral documents are subject to change at the sole discretion of Horizon Hobby, LLC. For up-to-date product literature, visit horizonhobby.com and click on the support tab for this product.

Meaning of Special Language

The following terms are used throughout the product literature to indicate various levels of potential harm when operating this product:

NOTICE: Procedures, which if not properly followed, create a possibility of physical property damage AND a little or no possibility of injury.

CAUTION: Procedures, which if not properly followed, create the probability of physical property damage AND a possibility of serious injury.

WARNING: Procedures, which if not properly followed, create the probability of property damage, collateral damage, and serious injury OR create a high probability of superficial injury.

WARNING: Read the ENTIRE instruction manual to become familiar with the features of the product before operating. Failure to operate the product correctly can result in damage to the product, personal property and cause serious injury.

This is a sophisticated hobby product. It must be operated with caution and common sense and requires some basic mechanical ability. Failure to operate this Product in a safe and responsible manner could result in injury or damage to the product or other property. This product is not intended for use by children without direct adult supervision. Do not use with incompatible components or alter this product in any way outside of the instructions provided by Horizon Hobby, LLC. This manual contains instructions for safety, operation and maintenance. It is essential to read and follow all the instructions and warnings in the manual, prior to assembly, setup or use, in order to operate correctly and avoid damage or serious injury.

Age Recommendation: Not for children under 14 years. This is not a toy.

Safety Precautions and Warnings

- Always keep a safe distance in all directions around your model to avoid collisions or injury. This model is controlled by a radio signal subject to interference from many sources outside your control. Interference can cause momentary loss of control.
- Always operate your model in open spaces away from full-size vehicles, traffic and people.
- Always carefully follow the directions and warnings for this and any optional support equipment (chargers, rechargeable battery packs, etc.).
- Always keep all chemicals, small parts and anything electrical out of the reach of children.
- Always avoid water exposure to all equipment not specifically designed and protected for this purpose. Moisture causes damage to electronics.
- Never place any portion of the model in your mouth as it could cause serious injury or even death.

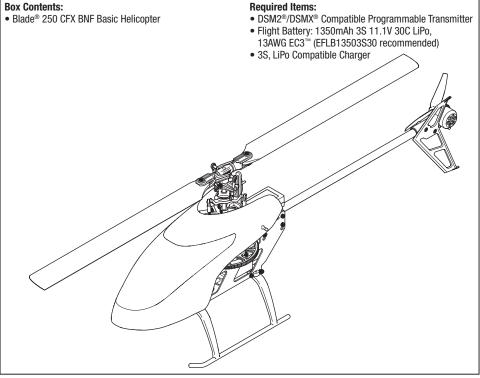
- Never operate your model with low transmitter batteries.
- Always keep aircraft in sight and under control.
- Always move the throttle fully down at rotor strike.
- Always use fully charged batteries.
- Always keep transmitter powered on while aircraft is powered.
- · Always remove batteries before disassembly.
- Always keep moving parts clean.
- · Always keep parts dry.
- Always let parts cool after use before touching.
- Always remove batteries after use.
- · Never operate aircraft with damaged wiring.
- Never touch moving parts.

WARNING AGAINST COUNTERFEIT PRODUCTS: If you ever need to replace your Spektrum receiver found in a Horizon Hobby product, always purchase from Horizon Hobby, LLC or a Horizon Hobby authorized dealer to ensure authentic high-quality Spektrum product. Horizon Hobby, LLC disclaims all support and warranty with regards, but not limited to, compatibility and performance of counterfeit products or products claiming compatibility with DSM or Spektrum technology.

Table of Contents

Specifications								
Length	18.2 in (463mm)	Tail Rotor Diameter	3.25 in (82.5mm)					
Height	7.1 in (180 mm)	Flying Weight	16.1oz (457 g)					
Main Rotor Diameter	21.7 in (550mm)							

Box Contents:



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3

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First Flight Preparation

- · Remove and inspect contents
- Begin charging the flight battery
- · Program your computer transmitter
- · Install the flight battery in the helicopter (once it has been fully charged)
- · Bind your transmitter
- Familiarize yourself with the controls
- · Find a suitable area for flving

Transmitter Setup Table

Flying Checklist

Always turn the transmitter on first

- □ Plug the flight battery into the lead from the ESC Allow the receiver and ESC to initialize and arm properly
- □ Fly the model Land the model
- Unplug the flight battery from the ESC Always turn the transmitter off last

The rates given in the following tables are recommended settings. The values may be adjusted up or down to suit the flying style of the user.

DX6i															
SETUP LIST		ADJ	JST LIS	T											
Model Type		TRA	/EL AD	J				D/R & Expo							
HE	ELI	Char	nel		Tra	vel		Chan		Sw Pos		D/R		Expo	
REVERSE		THRC)		100/	/100		AILE		0		100		+2	5
Channel	Direction	AILE			100/	/100		AILE		1		75		+2	5
THRO	N	ELEV			100/	/100		ELEV		0		100		+2	5
AILE	N	RUDI)		100/	/100				1		75		+2	5
ELEV	N	GYRC)		100/100			RUDD		0		100		+25	
RUDD	N	PITC	ITC 100/100					11000		1		75		+25	
GYRO	N	GYRO	GYRO							Mix 1					
PITC	R	RATE	SW-F.I	MODE						GYRO->GYRO ACT				Γ	
Swash Type		0	88	8%	NO	RM		0		Rate	D+125	+125% U+125%			
1 servo	Normal	1	12	2%	STL	JNT		1		SW		ELE D/	/R 1	RIM –	INH
D/R COMBI		Throt	tle Cur	ve						Pitch Curve					
D/R SW	AILE	Swite	h Pos	Pos	Pos	Pos	Pos	Pos		Switch Pos	Pos	Pos	Pos	Pos	Pos
Timer	7.022	(FM	ode)	1	2	3	4	5		(F Mode)	1	2	3	4	5
Down Timer	5:00	NO	RM	0	25	50	75	100		NORM	30	40	50	75	100
Switch	THR CUT	ST	JNT	80	80	80	80	80		STUNT	0	25	50	75	100
	1	Panic	Mode () pera	tion					HOLD	25	37	50	75	100
Modulation			D/R Sv												
AUTO DSN	TO DSMX-ENABLE Sw Pos 0 = Panic Mode Off														

Sw Pos 0 = Panic Mode Off Sw Pos 1 = Panic Mode On

Once the model has returned to level you must manually return the Panic Mode Switch to the off position otherwise the cyclic and tail rotor controls will be reduced.

DX7s, DX8

SYSTEM SETU	P	FUNC	TION LIST												
Model Type		Servo	Setup												
HELI	Chan	Trave	Travel		Revers	e		Cha	an Ti	ravel		Reverse)	
Swash Type THR 100/100 Normal					GEF	R 10	0/100		N	Normal					
1 servo N	ormal	AIL	100/10	-		Norma			PIT		0/100			ormal	
F-Mode Setup		ELE	100/10	-		Norma			AX2	2 10	0/100		N	ormal	
		RUD	100/10	0		Norma	l								
Flight Mode	F Mode	D/R &	D/R & Expo				Th	roti	tle Cı	irve					
Hold	Hold		Switch Pos				Sw	vitc	h Pos	s (F Mode)					
SW Select		Chan	(Ail D/R)	D/	R	Expo	DX7s		7s	DX8	Pt 1	Pt 2	Pt 3	Pt 4	Pt 5
Trainer	Aux 2		0	100/		+25		Ν		Ν	0	25	50	75	100
F Mode	Gear	AILE	1	100/	100	+25				1	80	80	80	80	80
Gyro	INH		2	75/	-	+25		1		2	100	100	100	100	100
Mix	INH		0	100/		+25	H	HOL	D	HOLD	0	0	0	0	0
Hold	INH	ELEV	1	100/		+25	Pit	Pitch Curve							
Knob	INH		2	75/	-	+25	Sw	vitc	h Pos	s (F Mode)					
Frame Rate			0	100/		+25		DX7	's	DX8	Pt 1	Pt 2	Pt 3	Pt 4	Pt 5
		RUDD	1	100/		+25		Ν	Í	Ν	30	40	50	75	100
11ms			2	75/	75	+25				1	0	25	50	75	100
	DSMX						1		2	0	25	50	75	100	
Panic Mode Ope							H	HOL	D	HOLD	25	37	50	75	100
Trainer/Bind Bu Pressed = Pau						Tin	ner								

Pressed = Panic Mode On Released = Panic Mode Off

0/75	+25			1	0	25	50	Γ
		1		2	0	25	50	Γ
		HOLD	H	OLD	25	37	50	
		Timer						
		Mode			C	count	Down	
		Time				5:00	Tone	
		Start		Throttle Out				
		Over				25	%	

DX6

DXD														
SYSTEM SETU	P	FUNC	TION LIST											
Model Type		Servo	Setup											
HEL		Chan	Travel		Re	verse		Chan		Trav	el	Reverse		
Swash Type		THR	100/100 Normal					RUD	_	100/1		Normal		
Norm	al	AIL	100/10	-		rmal		GER		100/1			Norma	
F-Mode Setup		ELE	E 100/100 Normal					PIT		100/1	00		Norma	
Switch 1	Switch B	D/R &	Ехро					Throttle (Curv	/e				
Hold Switch	Switch H	Chan	Sw (F) Pos		D/R	Expo		Sw (B) Po	os	Pt 1	Pt 2	Pt 3	Pt 4	Pt 5
Channel Assic		AILE	0 100/10			+25		Ν		0	25	50	75	100
Channel Input Config			1		5/75	+25		1		80	80	80	80	80
	It Config	ELEV	0	10	0/100	+25		HOLD		0	0	0	0	0
1 Throttle		LLEV	1		5/75	+25	I	Pitch Curve						
2 Aileron		RUDD	0	10	0/100	+25	Ľľ	N	Т	30	40	50	75	100
3 Elevator		nobb	1	7	5/75	+25		1		0	25	50	75	100
4 Rudder		Gyro						HOLD		25	37	50	75	100
5 Gear	Switch B		In	hibit			Ī	Mixing						
6 Collective		Timer					i ľ					Norma	1	_
Frame Rate		Mode		Соц	nt Down					Chan	nels	-	- > Ge	er
11ms Time					5:00			P-Mix 1		Rate		0/-125		5
DSM	DSMX Start			Throttle Out						Offse	t	100		
Papio Modo Op	nic Mode Operation				25%					Switch		Switch I		
Bind / I Button		One 1	lime 🛛	I	nhibit					Positi	on	0		1

Bind / I Button Pressed = Panic Mode On

Released = Panic Mode Off

ΈN

DX7 (G2), DX8 (G2), DX9, DX18, DX20

SYSTEM SETU	Р	FUNC	FUNCTION LIST										
Model Type		Servo	Setup										
HEL		Chan	Travel		Rev	/erse	Τ	Chan Tra		vel Reve		Revers	e
Swash Type		THR	100/100	0	No	rmal		PIT	100/1	00		Norma	
Norm	al	AIL	100/100	0	No	rmal		AX2	100/1	00		Norma	l
		ELE	100/100	-	No	rmal		AX3	100/1			Norma	l I
F-Mode Setup		RUD	100/100	0	No	rmal		AX4	100/1	00		Norma	
Switch 1	Switch B	GER	100/100	0	No	rmal							
Switch 2	Inhibit	D/R &	D/R & Expo					Throttle Cu	rve				
Hold Switch	Switch H	Chan	Sw (F) Pos	-) Pos D/R Expo			- 85	Sw (B) Pos		Pt 2	Pt 3	Pt 4	Pt 5
	0 1	Unan	0		100/100		f	N	0	25	50	75	100
Channel Assign		AILE	1)/100	+25	F	1	80	80	80	80	80
Channel Inpu	ut Config		2	75	5/75	+25	Ē	2	100	100	100	100	100
1 Throttle			0	100)/100	+25		Pitch Curv	9				
2 Aileron		ELEV	1	100)/100	+25	E	Sw (B) Pos	Pt 1	Pt 2	Pt 3	Pt 4	Pt 5
3 Elevator			2	75	5/75	+25		Ν	30	40	50	75	100
4 Rudder			0	100)/100	+25		1	0	25	50	75	100
5 Gear	Switch B	RUDD	1		/100	+25		2	0	25	50	75	100
6 Collective			2	75	75/75 +25		L	HOLD	25	37	50	75	100
7 AUX 2	Switch I	Gyro	Gyro					Timer					
Frame Rate	,		Inl	hibit				Mode	(Count Down			
								Time			5:0	-	
11m	5							Start			Throttl	e Out	

6

Start

Over One Time Throttle Out

25%

Inhibit

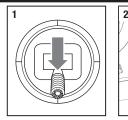
Panic Mode Operation

DSMX

Bind / I Button

Pressed = Panic Mode On Released = Panic Mode Off

Installing the Flight Battery

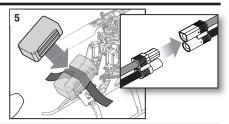




- 2. Power ON the transmitter.
- 3. Center all trims.
- 4. Attach the hook material to the helicopter frame and the loop material to the flight battery.
- 5. Install the flight battery on the helicopter frame. Secure the flight battery with the hook and loop strap.

NOTICE: If the flight battery strap is pulled too tight, it may result in a vibration or the tail rotor may drift to the right during flight. If you experience either of these issues, loosen the strap slightly and fly again.

6. Connect the battery connector to the ESC, noting correct polarity.



CAUTION: Connecting the battery to the ESC with reversed polarity will cause damage to the ESC, the battery or both. Damage caused by incorrectly connecting the battery is not covered under warranty.

7. Place the helicopter on a flat surface and leave it still until the ESC beeps twice and the LED glows solid, indicating initialization is complete.

If you experience issues during initialization, refer to the Troubleshooting Guide at the back of the manual.

CAUTION: Always disconnect the Li-Po battery from the aircraft when not flying to avoid over-discharging the battery. Batteries discharged to a voltage lower than the lowest approved voltage may become damaged, resulting in loss of performance and potential fire when batteries are charged.

Transmitter and Receiver Binding

This product requires an approved Spektrum DSM2[®]/DSMX[®] compatible transmitter. Visit *www.bindnfly.com* for a complete list of approved transmitters.

General Binding Procedure

1. Disconnect the flight battery from the helicopter.

2. Refer the Transmitter Setup Table to correctly setup your transmitter.

3. Lower the throttle stick to the lowest position. Set all trims to the center position.

4. Power off the transmitter and move all switches to the 0 position. Move the throttle to the low/off position.

5. Install the bind plug in the receiver BIND/PROG port (far left side of the receiver).

6. Connect the flight battery to the ESC. The receiver LED flashes, indicating it is in bind mode.

7. Put the transmitter into bind mode while powering on the transmitter.

8. Release the bind button/switch after 2–3 seconds. The helicopter is bound when the LED on the receiver turns solid.

9. Disconnect the flight battery and power the transmitter off.

CAUTION: When using a Futaba[®] transmitter with a *Spektrum*TM *DSM2*[®] module, you must reverse the throttle channel and re-bind. Refer to your *Spektrum* module manual for binding and failsafe instructions. Refer to your Futaba transmitter manual for instructions on reversing the throttle channel.

SAFE® Technology

Revolutionary SAFE[®] (Sensor Assisted Flight Envelope) technology uses an innovative combination of multi-axis sensors and software that allows model aircraft to know its position relative to the horizon. This spatial awareness is utilized to create a controlled flight envelope the aircraft can use to maintain a safe region of bank and pitch angles so you can fly more safely. Far beyond stability, this level of protection offers multiple modes so the pilot can choose to develop his or her skills with a greater degree of security and flight control that always feels crisp and responsive.

Flight Mode and Rate Selection

In **Stability Mode** the bank angle is limited. When the cyclic stick is released the model will return to level.

In **Intermediate Mode** the bank angle is not limited. When the cyclic stick is released the model will not return to level. This mode is great for learning forward flight and basic aerobatics such as stall turns and loops. SAFE technology delivers:

• Flight envelope protection you can enable at the flip of a switch.

• Multiple modes let you adapt SAFE technology to your skill level instantly.

Best of all, sophisticated SAFE technology doesn't require any work to enjoy. Every aircraft with SAFE installed is ready to use and optimized to offer the best possible flight experience.

FlySAFERC.com

In **Agility Mode** the bank angle is not limited. When the cyclic sticks is released the model will not return to level. This mode is great for 3D aerobatics such as stationary flips and tic tocs. Change rates by moving the two-position dual rate switch.

- Low rate reduces the control rates, providing an easier to fly model. Beginners should use low rate for initial flights.
- High rate provides full control and should be used by intermediate and experience pilots.

Panic Recovery

If you get into distress while flying in any mode, push and hold the Bind/Panic Switch and move the control sticks to their neutral position. SAFE technology will immediately return the aircraft to an upright level attitude, if the aircraft is at a sufficient height with no obstacles in its path. Return the collective stick to 50% and release the Panic Switch to turn off Panic Recovery and return to the current flight mode. **NOTICE:** Before releasing the panic switch, make sure the collective stick has been returned to the 50% position. Once the panic switch has been released, full negative collective becomes available, which could cause the 250 CFX to descend rapidly.

- This mode is intended to provide the pilot with the confidence to continue to improve their flight skills.
- Move the collective stick to 50% and return all other transmitter controls to neutral for the quickest recovery.
- Once the model has reached a level upright attitude, the negative collective is reduced to prevent the user from pushing the model into the ground.

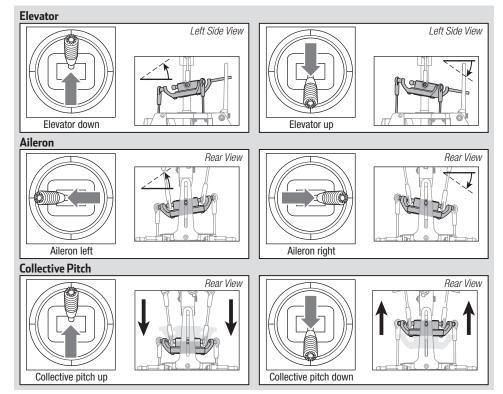
Throttle Hold

Throttle hold is used to prevent the motor from powering on inadvertently. For safety, turn throttle hold ON any time you need to touch the helicopter or check the direction controls. Throttle hold is also used to turn off the motor quickly if the helicopter is out of control, in danger of crashing, or both. The blades will continue to spin briefly when throttle hold is activated. Pitch and direction control is still maintained.

Control Tests

Ensure the throttle hold is ON when doing the direction control tests. Test the controls prior to the first flight to ensure the servos, linkages and parts operate correctly.

If the controls do not react as shown in the illustrations below, confirm the transmitter is programmed correctly before continuing on to the Motor test.



Motor

Place the helicopter outdoors on a clean, flat and level surface (concrete or asphalt) free of obstructions. Always stay clear of moving rotor blades.



CAUTION: Keep pets and other animals away from the helicopter. Animals may injure themselves if they attack or run toward the helicopter.

- 1. Both motors beep 3 times when the helicopter's ESC arms properly. Before you continue, confirm that throttle is at full low position.
- 2. Turn Throttle Hold OFF.

WARNING: Stay at least 30 feet (10 meters) away from the helicopter when the motor is running. Do not attempt to fly the helicopter at this time.

3. Slowly increase the throttle until the blades begin to spin. The main blades should spin clockwise when viewing the helicopter from the top. The tail rotor blades should spin counterclockwise when viewing the helicopter from the right side.

NOTICE: If the main rotor blades are spinning counterclockwise, reduce the throttle to low immediately. Disconnect the battery from the helicopter and reverse any two motor wire connections to the ESC and repeat the motor control test.

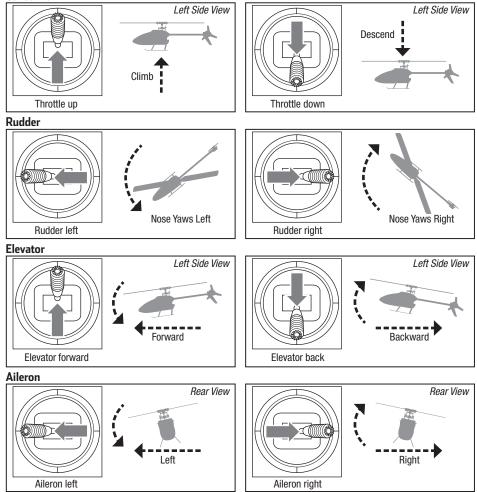
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Understanding the Primary Flight Controls

If you are not familiar with the controls of your 250 CFX, take a few minutes to familiarize yourself with them before attempting your first flight.

Collective



Consult your local laws and ordinances before choosing a location to fly your aircraft.

We recommend flying your aircraft outside in calm winds or inside a large gymnasium. Always avoid flying near houses, trees, wires and buildings. You should also be careful to avoid flying in areas where there are many people, such as busy parks, schoolyards or soccer fields.

It is best to fly from a smooth flat surface as this will allow the model to slide without tipping over. Keep the helicopter approximately 2 ft (600mm) above the ground. Keep the tail pointed toward you during initial flights to keep the control orientation consistent. Releasing the stick in Stability Mode will allow the helicopter to level itself. Activating the Panic Recovery button will level the helicopter quickly. If you become disoriented while in Stability Mode, slowly lower the throttle stick to land softly.

During initial flights, only attempt takeoff, landing and hovering in one spot.

Takeoff

NOTICE: If the main motor or tail motor do not startup properly when throttle is first applied, immediately return the throttle to idle and try again. If the problem persists, disconnect the flight battery, check for binding in the gear train and ensure no wires have become entangled within the gears.

Place the model onto a flat, level surface free of obstacles and walk back 30 feet (10 meters). Slowly increase the throttle until the model is approximately 2 ft. (600mm) off the ground and check the trim so the model flies as desired. Once the trim is adjusted, begin flying the model.

Hovering

Making small corrections on the transmitter, try to hold the helicopter in one spot. If flying in calm winds, the model should require almost no corrective inputs. After moving the cyclic stick and returning it to center, the model should level itself. The model may continue to move due to inertia. Move the cycle stick in the opposite direction to stop the movement.

After you become comfortable hovering, you can progress into flying the model to different locations, keeping the tail pointed towards you at all times. You can also ascend and descend using the throttle stick. Once you're comfortable with these maneuvers, you can attempt flying with the tail in different orientations. It is important to keep in mind that the flight control inputs will rotate with the helicopter, so always try to picture the control inputs relative to the nose of the helicopter. For example, forward will always drop the nose of the helicopter.

Low Voltage Cutoff (LVC)

LVC decreases the power to the motors when the battery voltage gets low. When the motor power decreases and the red LED on the ESC flashes, land the aircraft immediately and recharge the flight battery.

LVC does not prevent the battery from over-discharge during storage.

NOTICE: Repeated flying to LVC will damage the battery.

Landing

To land, slowly decrease the throttle while in a low-level hover. After landing, disconnect and remove the battery from the aircraft after use to prevent trickle discharge. Fully charge your battery before storing it. During storage, make sure the battery charge does not fall below 3V per cell.

Advanced Settings

The 250 CFX default settings are appropriate for most users. We recommend flying with the default parameters before making any adjustments.

Gain Parameters

1. Cyclic P Gain Adjustment (Default 100%)

Higher gain will result in greater stability. Setting the gain too high may result in random twitches if your model has an excessive level of vibration. High frequency oscillations may also occur if the gain is set too high.

Lower gain will result in less stability. Too low of a value may result in a less stable model, particularly outdoors in winds.

If you are located at a higher altitude or in a warmer climate, higher gains may be beneficial—the opposite is true for lower altitude or colder climates.

WARNING: To ensure your safety, always disconnect the motor wires from the ESC before performing the following steps. After you have completed the adjustments, reconnect the motor wires to the ESC before attempting to fly the model.

2. Cyclic I Gain Adjustment (Default 100%)

Higher gain will result in the model remaining still, but may cause low frequency oscillations if increased too far. *Lower gain* will result in the model drifting slowly.

If you are located at a higher altitude or in a warmer climate, higher gains may be beneficial—the opposite is true for lower altitude or colder climates.

3. Cyclic D Gain Adjustment (Default 100%)

Higher gain will improve the response rate of your inputs. If the gain is raised too much, high frequency oscillations may occur.

Lower gain will slow down the response to inputs.

4. Cyclic Response (Default 100%)

Higher cyclic response will result in a more aggressive cyclic response.

Lower cyclic response will result in a less aggressive cyclic response.

5. Tailrotor P Gain Adjustment (Default 100%)

Higher gain will result in greater stability. Setting the gain too high may result in random twitches if your model has an excessive level of vibration. High frequency oscillations may also occur if the gain is set too high.

Lower gain may result in a decrease in stability. Too low of a value may result in a less stable model particularly outdoors in winds.

If you are located at a higher altitude or in a warmer climate, higher gains may be beneficial—the opposite is true for lower altitude or colder climates.

Entering Gain Adjustment Mode

- 1. Lower the throttle stick to the lowest position.
- 2. Power ON the transmitter.
- 3. Install the flight battery on the helicopter frame, securing it with the hook and loop strap.
- 4. Connect the battery connector to the ESC.
- Place the helicopter on a flat surface and leave it still until the orange receiver LED glows solid, indicating initialization is complete.

6. Tailrotor I Gain Adjustment (Default 100%)

Higher gain results in the tail remaining still. If the gain is raised too far, low speed oscillations may occur. Lower gain will result in the tail drifting in flight over time.

If you are located at a higher altitude or in a warmer climate, higher gains may be beneficial—the opposite is true for lower altitude or colder climates.

7. Tailrotor D Gain Adjustment (Default 100%)

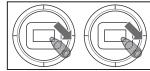
Higher gain will improve the response rate to your inputs. If raised too far, high frequency oscillations may occur. *Lower gain* will slow down the response to inputs, but will not have an effect on stability.

8. Tailrotor Adaptive Filtering

Higher gain will reduce oscillations during high speed flight and when using large amounts of collective.

Lower gain will improve tail performance but may lead to tail oscillations.

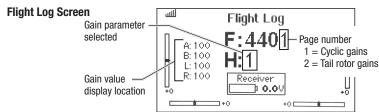
6. Move and hold both transmitter sticks to the bottom right corner as shown.



- Press and hold the bind/panic switch until the swash servos move.
- Release the sticks and the bind/panic switch. The model is now in Gain Adjustment Mode.
- 9. Proceed to Adjusting the Gain Values to make any desired changes.

Adjusting the Gain Values

If you are using a Spektrum[™] telemetry-enabled transmitter, the gain adjustments can be viewed on the Flight Log screen. Refer to your transmitter instructions to locate this screen. The gain parameter currently selected will flash on the transmitter screen. If you are not using a Spektrum telemetry-enabled transmitter, the parameter and gain values are indicated by the position of the swashplate on the helicopter.



Once you have entered Gain Adjustment Mode, move the cyclic stick right and left to select the gain parameter to adjust. Moving the stick right will select the next parameter. Moving the stick left will select the previous parameter.

The selected gain parameter is indicated on the Flight Log screen above and by the lean of the swashplate on the roll axis as shown in the table at the right.

Parameter #	Display location	Swash Position	Page #
1	А	100% to the Left	1
2	В	70% to the Left	1
3	L	40% to the Left	1
4	R	10% to the Left	1
5	А	10% to the Right	2
6	В	40% to the Right	2
7	L	70% to the Right	2
8	R	100% to the Right	2

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The current gain value for the selected parameter is indicated on the Flight Log screen and by the angle of the swashplate (forward or backward) as shown in the table at the right.

Move the cyclic stick forward or backward to adjust the gain value. Moving the stick *forward* will increase the gain value. Moving the stick *backward* will decrease the gain value.

It is always best to adjust one gain at a time. Make small adjustments (5% or less) and test fly the model to evaluate the adjustments that were made.

If you would like to reset the current gain value to the default value of 100%, move and hold the rudder stick full right for 1 second. The swash will level on the pitch axis, indicating a 100% gain setting.

Servo Adjustment

Your helicopter was setup at the factory and test flown. The servo adjustment steps are usually only necessary in special circumstances, such as after a crash or if a servo or linkage is replaced.

Entering Servo Adjustment Mode

- 1. Lower the throttle stick to the lowest position.
- 2. Power ON the transmitter.
- 3. Install the flight battery on the helicopter frame, securing it with the hook and loop strap.
- 4. Connect the battery connector to the ESC.
- Place the helicopter on a flat surface and leave it still until the orange receiver LED glows solid, indicating initialization is complete.

Adjusting the Servo Neutral Position

With the model in Servo Adjustment Mode, the control stick and gyro inputs are disabled and the servos are held in the neutral position. Check the position of the servo arms to see if they are perpendicular to the servos.

- If the arms are perpendicular to the servos, no adjustment is necessary.
 Evit Source Adjustment Made
 - Exit Servo Adjustment Mode.
- If one or more servo arm is not perpendicular to the servos, continue the servo adjustment process.

While watching the swashplate servos, apply right cyclic and release. One of the servos will jump, indicating which servo is selected. Press right cyclic and release until the servo that needs to be adjusted is selected.

Saving the Servo Adjustments

Before saving your adjustments and exiting servo adjustment mode, verify the swashplate is level and both main rotor blades are at 0 degrees. If they are not, make linkage adjustments as necessary.

1. Lower the throttle stick to the lowest position and release the sticks.

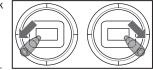
Swash Position	Gain Value
Full backward	0%
50% backward	50%
Level forward and backward	100%
50% forward	150%
Full forward	200%

Saving the Gain Adjustments

- 1. Lower the throttle stick to the lowest position and release the sticks.
- 2. Press and hold switch I until the swash servos move.
- 3. Release switch I to save the gain adjustments.
- 4. Reconnect the main drive motor to the ESC. Your model is now ready for flight.

WARNING: To ensure your safety, always disconnect the motor wires from the ESC before performing the following steps. After you have completed the adjustments, reconnect the motor wires to the ESC before attempting to fly the model.

 Hold the left stick to the bottom left corner and the right stick to the bottom right corner as shown.



- Hold the bind/panic switch until the swash servos move.
- 8. Release the sticks and the bind/panic switch. The model is now in Servo Adjustment Mode.
- 9. Proceed to Adjusting the Servo Neutral Position to make any desired changes.

Once the servo you wish to adjust is selected, move the cyclic stick forward or backward to adjust the servo neutral position in the desired direction.

If you would like to reset the current servo to the default neutral position, hold the rudder stick full right for 1 second.

The range of adjustment is limited. If you are unable to adjust the servo arm to be perpendicular to the servo, you must reset the servo to the default neutral position, remove the servo arm and place it back onto the servo as close to perpendicular as possible. You may then adjust the servo neutral position using the forward/backward cyclic stick.

- 2. Press and hold switch I until the swash servos move.
- 3. Release switch I to save the servo adjustments.
- 4. Reconnect the main drive motor to the ESC. Your model is now ready for flight.

All of the settings are stored internally, so your adjustments will be maintained each time you initialize the model.



Trim Flight

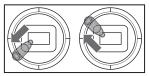
Perform this procedure if the model is not performing well or has been recently rebuilt from a crash.

The trim flight procedure was performed during the factory test flight and only needs to be performed if you notice the model is not returning to level consistently or if the model does not remain still during stationary pirouettes. The trim flight is used to determine the optimal settings for SAFE® technology during flight.

The trim flight must be performed in calm conditions.

Entering Trim Flight Mode

- 1. Lower the throttle stick to the lowest position.
- 2. Center all trims.
- 3. Power ON the transmitter.
- 4. Install the flight battery in the helicopter.
- 5. Connect the battery connector to the ESC.
- Place the helicopter on a flat surface and leave it still until the motor beeps twice and the ESC LED glows solid, indicating initialization is complete.
- 7. Place the helicopter where you are going to take off.
- Move and hold the left stick to the bottom left corner and the right stick to the top left corner as shown.



- 9. Press and hold the bind/panic switch until the swashplate rotates around once.
- 10. Release the sticks and bind/panic switch.
- 11. The model is ready for the trim flight.

Performing the Trim Flight

- Slowly increase the throttle to lift the model into a stationary hover. Make corrections as necessary to keep the model still. Evaluation does not begin until the throttle stick is over 50% and the sticks are centered. Making corrections will not affect the result but a longer flight may be necessary.
- 2. Keep the model stationary in a hover for a total of 30 seconds. Sliding and slow movements are okay. The main goal is to keep the rotor disk level.
- 3. Once you are satisfied with the trim flight, land the model.

Exiting Trim Flight Mode

- 1. After landing, lower the throttle stick to the lowest position.
- Press and hold the bind/panic switch for 2 seconds, or until the swashplate twitches, indicating the servo positions and attitude values have been recorded and trim flight mode has been exited.

Flight Test

After performing the trim flight, test-fly the model to evaluate the leveling characteristics.

- The model should return to level flight consistently.
- During takeoff, the model should lift off with minimal corrections.
- During a hover, the control stick should remain close to center. Small corrections are acceptable.

If the model performs poorly or does not level properly after the trim flight, retry the entire

trim flight procedure. If the problem persists, inspect the model for damaged components,

a bent shaft or anything that may result in increased vibration. The trim flight may not record the correct values due to excessive vibration, flying in wind or the model not staying level. In these cases, shorter trim flights may be necessary. Try the 30-second, level trim flight without corrections mentioned above first. If the leveling characteristics are not satisfactory, gradually shorten the trim flights, checking for improvements until the model performs as described.

Calibration Procedure

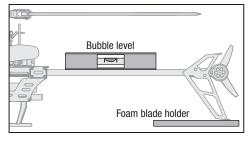
If the Blade 250 CFX is experiencing drift issues after completing the trim flight procedure located at *www.bladehelis.com*, perform the following calibration. The calibration procedure may also be needed following crash repairs.



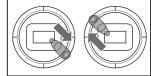
WARNING: Before beginning the calibration procedure, disconnect the main motor and tail motor leads to prevent accidental motor startup during calibration.

To perform the calibration procedure:

- 1. Ensure the surface used for calibration is level.
- 2. Power on the transmitter and helicopter, allowing them to initialize.
- 3. Turn Throttle Hold ON.
- Ensure the main motor and tail motor leads are disconnected. Set the flight mode switch to Intermediate Mode (FM1).
- 5. Using a bubble level as shown below, level the helicopter by placing the Blade 250 CFX foam blade holder under the tail fin. Use additional items, as necessary, to build up under the tail fin until the tail boom is level.



- 6. Hold the left stick to the bottom right corner, the right stick to the upper left corner and press the bind button until the LED on the receiver flashes once.
- 7. Release both sticks and the bind button.
- 8. The LED on the receiver will remain solid for 1-2 minutes while the calibration takes place. Do not move the



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helicopter until the calibration is completed. If the LED begins blinking rapidly, an error has occurred. Begin the calibration procedure again, starting with step 1.

- 9. After the calibration is successfully completed, the receiver LED will blink slowly (2 seconds on, 2 seconds off).
- 10. Power the helicopter off.
- 11. Reconnect the main motor and tail motor wires.
- 12. Perform the trim flight procedure as shown in the Advanced Settings Addendum available at *www.bladehelis.com*.
- 13. During subsequent flights after the trim flight, the helicopter should return to within 5 degrees of level consistently.

Post-Flight Inspection and Maintenance Checklist

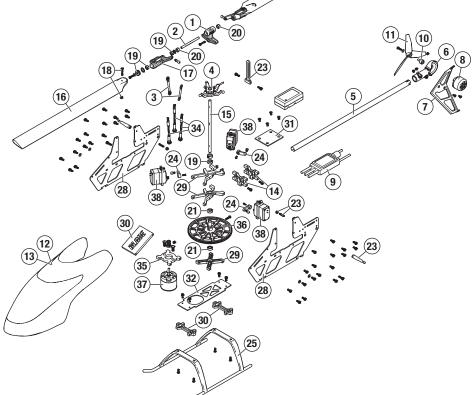
\checkmark		
	Ball Links	Make sure the plastic ball link holds the control ball, but is not tight (binding) on the ball. When a link is too loose on the ball, it can separate from the ball during flight and cause a crash. Replace worn ball links before they fail.
	Cleaning	Make sure the battery is not connected before cleaning. Remove dust and debris with a soft brush or a dry, lint-free cloth.
	Bearing s	Replace bearings when they become notchy (sticky in places when turning) or draggy.
	Wiring	Make sure the wiring does not contact moving parts. Replace damaged wiring and loose connectors.
	Fasteners	Make sure there are no loose screws, other fasteners or connectors. Do not over-tighten metal screws in plastic parts. Tighten screws so the parts are mated together, then turn the screw only 1/8th of a turn more.
	Rotors	Make sure there is no damage to rotor blades and other parts which move at high speed. Damage to these parts includes cracks, burrs, chips or scratches. Replace damaged parts before flying. Verify both main rotor blades have the correct and equal tension in the blade grips. When the helicopter is held up sideways, the main blades should support their own weight. When the helicopter is shaken lightly, the blades should fall.
	Tail	Inspect the tail rotor for damage and replace if necessary. Verify the tail motor bolts, tail rotor adapter bolts and tail motor mount bolts are properly tightened. Inspect the tail boom for any damage and replace if necessary.
	Mechanics	Inspect the main frame and landing gear for damage and replace if necessary. Check the mainshaft for vertical play and adjust the locking collar if necessary. Verify that the main gear mesh is correct and that no tight spots exist in the 360 degree rotation. Inspect all wires for damage and replace as necessary.

Troubleshooting Guide

Problem	Possible Cause	Solution					
Helicopter control response is inconsistent or requires extra trim to neutralize movement	Aircraft was not initialized prop- erly or a vibration is interfering with the sensor operation	Disconnect the flight battery, center the control trim and re-initialize the helicopter					
Helicopter will not respond to throttle	Throttle too high and/or throttle trim is too high	Disconnect the flight battery, place the throttle stick in the lowest position and lower the throttle trim a few clicks. Connect the flight battery and allow the model to initialize					
	Helicopter moved during initial- ization	Disconnect the flight battery and re-initialize the heli- copter while keeping the helicopter from moving					
	Flight battery charge is low	Completely recharge the flight battery					
Helicopter has reduced flight time or is under-	Flight battery is damaged	Replace the flight battery and follow the flight battery instructions					
powered	Flight conditions might be too cold	Make sure the battery is warm (room temperature) before use					
LED on receiver flashes	Transmitter too near aircraft dur- ing binding process	Power off the transmitter. Move the transmitter a larger distance from the aircraft. Disconnect and reconnect the flight battery to the aircraft. Follow the binding instructions					
rapidly and aircraft will not respond to transmitter (during binding)	Bind switch or button was not held while transmitter was pow- ered on	Power off transmitter and repeat bind process					
	Aircraft or transmitter is too close to large metal object, wireless source or another transmitter	Move aircraft and transmitter to another location and attempt binding again					

Problem	Possible Cause	Solution					
	The bind plug was not removed from the receiver after binding	Disconnect the flight battery, remove the bind plug from the receiver and reconnect the flight battery.					
LED on the receiver flashes	Less than a 5-second wait between first powering on the transmitter and connecting the flight battery to the helicopter	Leave the transmitter powered on. Disconnect and reconnect the flight battery to the helicopter					
rapidly and the helicopter will not respond to the transmitter (after binding)	The helicopter is bound to a different model memory (ModelMatch™ transmitters only)	Select the correct model memory on the transmitter. Disconnect and reconnect the flight battery to the helicopter					
	Flight battery or transmitter battery charge is too low	Replace or recharge batteries					
	Aircraft or transmitter is too close to large metal object, wireless source or another transmitter	Move aircraft and transmitter to another location and attempt connecting again					
Helicopter vibrates or shakes in flight	Damaged rotor blades, spindle or blade grips	Check main rotor blades and blade grips for cracks or chips. Replace damaged parts. Replace bent spindle					
Random movements in flight	Vibration	Verify the receiver is properly attached to the helicopter. Inspect mounting tape for damage. Verify that no wires are contacting the receiver. Inspect and balance all rotating components. Verify the main shaft and tail rotor adapter are not damaged or bent. Inspect mechanics for broken or damaged parts and replace as necessary					
Tail oscillation/wag or poor performance	Damaged tail rotor, main gear mesh, loose bolts, vibration	Verify that the boom support bolts are tight and the plastic boom support ends are properly adhered to the boom support rods. Inspect the tail rotor for damage. Verify that all bolts on the tail assembly are properly tightened. Verify main gear mesh and ensure no tight spots in the mesh through full rotation. Replace any damaged or worn components					
Drift in calm winds	Vibration, damaged linkage, damaged servo	Under normal operation the transmitter trims should not require adjustment and the center positions are memorized during initialization. If you find that trim adjustments are necessary after take off, verify the balance of all rotating components, ensure the linkages are not damaged and make sure the servos are in proper working condition					
Drift in wind	Normal	The model will drift with the wind but should remain level in flight. Simply hold the cyclic stick in the neces- sary position to keep the model stationary. The model must lean into the wind to remain stationary, if the model remains level then it will drift with the wind					
Panic Recovery or Return to Level does not level the	Model was not initialized on a level, still surface	Re-initialize the model on a level and still surface					
model	Model was not taken off of a level surface	Always lift off from a level surface					
	Battery strapped too tightly to the model	Loosen the battery strap					
Severe vibration	Rotating component out of balance	Check the main shaft, tail rotor, main rotor blades, main frame and adapter for damage, replace as necessary. Vibration must be minimized for Panic Recovery and Return to Level functions to work properly					

Exploded View



Parts Listings

	Part #	Description	
1	BLH1501	Main rotor head: Blade 230s	
2	BLH1502	Spindle set: Blade 230s	
3	BLH1504	Main rotor head linkage set: Blade 230s	
4	BLH1505	Swashplate: Blade 230s	
5	BLH1512	Tail boom: Blade 230s	
6	BLH1513	Tail motor mount: Blade 230s	
7	BLH1514	Vertical tail fin: Blade 230s	
8	BLH1515	Tail motor 3600kv: Blade 230s	
9	BLH4484	Dual Brushless ESC: 250 CFX	
10	BLH2020	Tail Rotor Hub Set: 200 SR X	
11	BLH2021	Tail Rotor Blade Set (2), White: 200 SR X	
12	BLH4481RE	Stock Canopy Red: 250 CFX	
13	BLH4481YE	Stock Canopy Yellow: 250 CFX	
14	BLH4482	Tail Boom Mount: 250 CFX	
15	BLH4483	Main Shaft w/ Spacer: 250 CFX	
16	BLH4501C	245mm CF Main Rotor Blade: 300 X, BSR	
17	BLH4502	Main Rotor Blade Grips: 300 X	
18	BLH4503	Main Rotor Blade Mounting Screw & Nut (2): 300 X	
19	BLH4504	Main Grip Bearing Kit: 300 X	

	Part #	Description		
20	BLH4505	Dampers (4): 300 X		
21	BLH4515	Bearings 4x8x3 (3): 300 X		
22	BLH4517	Canopy Mounts (2): 300 X		
23	BLH4518A	Aluminum Anti-Rotation Bracket/Guide: 300 X		
24	BLH4519A	Aluminum Servo Control Arms: 300 X		
25	BLH4520	Landing Gear Set: 300 X		
26	BLH4541	Mini Helicopter Main Blade Holder: 300 X		
27	BLH4544	Mounting Access, Screwdriver & Wrench: 300 X		
28	BLH4601	Main Frame: 300 CFX		
29	BLH4602	Bearing Blocks: 300 CFX		
30	BLH4603	Bottom Plate Mount: 300 CFX		
31	BLH4605	Gyro Mount: 300 CFX		
32	BLH4606	Bottom Plate: 300 CFX		
33	BLH4607	Battery Mount: 300 CFX		
34	BLH4608	Swash Links: 300 CFX		
35	BLH4612	Main Motor Mount: 300 CFX		
36	EFLH1509	Main Gear: BSR		
37	EFLM1160H	320H Helicopter Motor, 4500Kv: 300 X		
38	SPMSH3050	H3050 Sub-Micro Digital Heli Cyclic MG Servo		

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Optional Parts

Part #	Description	Part #	Description
EFLB13503S30	1350mAh 3S 11.1V 30C LiPo, 13AWG EC3	EFLC3016	3S DC Li-Po Balancing Charger: 3.5A
BLH1501A	Aluminum Main Rotor head : 230 S	EFLC4030	3.0-Amp Power Supply, 100-240V AC-12V DC
BLH1505A	Aluminum Swashplate : 230 S	EFLH1000	Micro/Mini Helicopter Pitch Gauge
BLH1513A	Aluminum Tail case set : 230 S		DX6 DSMX 6-Channel Transmitter Only
BLH1519A	Aluminum Blade grips : 230 S		DX7 DSMX 7-Channel Transmitter Only
BLH1578	Rotor Head Assembly: 230S		DX8 DSMX 8-Channel Transmitter Only
BLH1610	Pinion Gear, 10T 0.5M: B450, B400		DX9 DSMX 9-Channel Transmitter Only
BLH4612	Main Motor Mount: 300 CFX		DX18 DSMX 18-Channel Transmitter Only
EFLA261	Micro/Mini Heli Tool Assortment, 6 pc		DX20 DSMX 20-Channel Transmitter Only

Limited Warranty

What this Warranty Covers

Horizon Hobby, LLC, (Horizon) warrants to the original purchaser that the product purchased (the "Product") will be free from defects in materials and workmanship at the date of purchase.

What is Not Covered

This warranty is not transferable and does not cover (i) cosmetic damage, (ii) damage due to acts of God, accident, misuse, abuse, negligence, commercial use, or due to improper use, installation, operation or maintenance, (iii) modification of or to any part of the Product, (iv) attempted service by anyone other than a Horizon Hobby authorized service center, (v) Product not purchased from an authorized Horizon dealer, (vi) Product not compliant with applicable technical regulations, or (vii) use that violates any applicable laws, rules, or regulations.

OTHER THAN THE EXPRESS WARRANTY ABOVE, HORIZON MAKES NO OTHER WARRANTY OR REPRESENTATION, AND HEREBY DISCLAIMS ANY AND ALL IMPLIED WARRANTIES, INCLUDING, WITHOUT LIMITATION, THE IMPLIED WARRANTIES OF NON-INFRINGEMENT, MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. THE PURCHASER ACKNOWLEDGES THAT THEY ALONE HAVE DETERMINED THAT THE PRODUCT WILL SUITABLY MEET THE REQUIREMENTS OF THE PURCHASER'S INTENDED USE.

Purchaser's Remedy

Horizon's sole obligation and purchaser's sole and exclusive remedy shall be that Horizon will, at its option, either (i) service, or (ii) replace, any Product determined by Horizon to be defective. Horizon reserves the right to inspect any and all Product(s) involved in a warranty claim. Service or replacement decisions are at the sole discretion of Horizon. Proof of purchase is required for all warranty claims. SERVICE OR REPLACEMENT AS PROVIDED UNDER THIS WARRANTY IS THE PURCHASER'S SOLE AND EXCLUSIVE REMEDY.

Limitation of Liability

HORIZON SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY, REGARDLESS OF WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, TORT, NEGLIGENCE, STRICT LIABILITY OR ANY OTHER THEORY OF LIABILITY, EVEN IF HORIZON HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Further, in no event shall the liability of Horizon exceed the individual price of the Product on which liability is asserted. As Horizon has no control over use, setup, final assembly, modification or misuse, no liability shall be assumed nor accepted for any resulting damage or injury. By the act of use, setup or assembly, the user accepts all resulting liability. If you as the purchaser or user are not prepared to accept the liability associated with the use of the Product, purchaser is advised to return the Product immediately in new and unused condition to the place of purchase.

Law

These terms are governed by Illinois law (without regard to conflict of law principals). This warranty gives you specific legal rights, and you may also have other rights which vary from state to state. Horizon reserves the right to change or modify this warranty at any time without notice.

WARRANTY SERVICES Questions Assistance and Service

Questions, Assistance, and Services

Your local hobby store and/or place of purchase cannot provide warranty support or service. Once assembly, setup or use of the Product has been started, you must contact your local distributor or Horizon directly. This will enable Horizon to better answer your questions and service you in the event that you may need any assistance. For questions or assistance, please visit our website at www.horizonhobby. com, submit a Product Support Inquiry, or call the toll free telephone number referenced in the Warranty and Service Contact Information section to speak with a Product Support representative.

Inspection or Services

19

If this Product needs to be inspected or serviced and is compliant in the country you live and use the Product in, please use the Horizon Online Service Request submission process found on our website or call Horizon to obtain a Return Merchandise Authorization (RMA) number. Pack the Product securely using a shipping carton. Please note that original boxes may be included, but are not designed to withstand the rigors of shipping without additional protection. Ship via a carrier that provides tracking and insurance for lost or damaged parcels, as Horizon is not responsible for merchandise until it arrives and is accepted at our facility. An Online Service Request is available at http://www.horizonhobby.com/ content/service-center_render-service-center. If you do not have internet access, please contact Horizon Product Support to obtain a RMA number along with instructions for submitting your product for service. When calling Horizon, you will be asked to provide your complete name, street address, email address and phone number where you can be reached during business hours. When sending product into Horizon, please include your RMA number, a list of the included items, and a brief summary of the problem. A copy of your original sales receipt must be included for warranty consideration. Be sure your name, address, and RMA number are clearly written on the outside of the shipping carton.

NOTICE: Do not ship Li-Po batteries to Horizon. If you have any issue with a Li-Po battery, please contact the appropriate Horizon Product Support office.

Warranty Requirements

For Warranty consideration, you must include your original sales receipt verifying the proof-of-purchase date. Provided warranty conditions have been met, your

Product will be serviced or replaced free of charge. Service or replacement decisions are at the sole discretion of Horizon.

Non-Warranty Service

Should your service not be covered by warranty, service will be completed and payment will be required without notification or estimate of the expense unless the expense exceeds 50% of the retail purchase cost.

By submitting the item for service you are agreeing to payment of the service without notification. Service estimates are available upon request. You must include this request with your item submitted for service. Non-warranty service estimates will be billed a minimum of ½ hour of labor. In addition you will be billed for return freight. Horizon accepts money orders and cashier's checks, as well as Visa, MasterCard, American Express, and Discover cards. By submitting any item to Horizon for service, you are agreeing to Horizon's Terms and Conditions found on our website http://www.horizonhobby.com/content/service-center render-service-center.

ATTENTION: Horizon service is limited to Product compliant in the country of use and ownership. If received, a non-compliant Product will not be serviced. Further, the sender will be responsible for arranging return shipment of the un-serviced Product, through a carrier of the sender's choice and at the sender's expense. Horizon will hold non-compliant Product for a period of 60 days from notification, after which it will be discarded. 10/15

Country of Purchase	Horizon Hobby	Contact Information	Address	
	Horizon Service Center (Repairs and Repair Requests)	servicecenter.horizonhobby.com/ RequestForm/	 1 4105 Fieldstone Rd Champaign, Illinois, 61822 USA	
United States	Horizon Product Support	productsupport@horizonhobby.com		
of America	(Product Technical Assistance)	877-504-0233		
	Sales	websales@horizonhobby.com		
	Jaies	800-338-4639		
	Service/Parts/Sales:	sales@horizonhobby.co.uk	Units 1–4 , Ployters Rd, Staple Tye Harlow, Essex, CM18 7NS, United Kingdom	
United Kingdom	Horizon Hobby Limited	+44 (0) 1279 641 097		
Germany	Horizon Technischer Service	service@horizonhobby.de	Christian-Junge-Straße 1	
definally	Sales: Horizon Hobby GmbH	y GmbH +49 (0) 4121 2655 100 25337 Elmshorr		
France	Service/Parts/Sales:	infofrance@horizonhobby.com	11 Rue Georges Charpak 77127 Lieusaint, France	
TIANGE	Horizon Hobby SAS	+33 (0) 1 60 18 34 90		

Warranty and Service Contact Information

FCC Information

This device complies with part 15 of the FCC rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

CAUTION: Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This product contains a radio transmitter with wireless technology which has been tested and found to be compliant with the applicable regulations governing a radio transmitter in the 2.400GHz to 2.4835GHz frequency range.

Antenna Separation Distance

When operating your Spektrum transmitter, please be sure to maintain a separation distance of at least 5 cm between your body (excluding fingers, hands, wrists, ankles and feet) and the antenna to meet RF exposure safety requirements as determined by FCC regulations. The following illustrations show the approximate



5 cm RF exposure area and typical hand placement when operating your Spektrum transmitter.

IC Information

This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions:

(1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Compliance Information for the European Union

EU Compliance Statement: Horizon Hobby, LLC hereby declares that this product is in compliance with the essential requirements and other relevant provisions of the R&TTE and EMC Directives.

A copy of the EU Declaration of Conformity is available online at: http://www.horizonhobby.com/content/supportrender-compliance.

Instructions for disposal of WEEE by users in the European Union



This product must not be disposed of with other waste. Instead, it is the user's responsibility to dispose of their waste equipment by handing it over to a designated collections point for the recycling of waste electrical and electronic equipment. The separate collection and recycling of your waste equipment at the



time of disposal will help to conserve natural resources and make sure that it is recycled in a manner that protects human health and the environment. For more information about where you can drop off your waste equipment for recycling, please contact your local city office, your household waste disposal service or where you purchased the product.

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